

GOOSKY S2 直升机

T16SZ Futaba 遥控器参数设置

1. 新建一个模型（保持初始化）

Create a new model (keep it initialized)



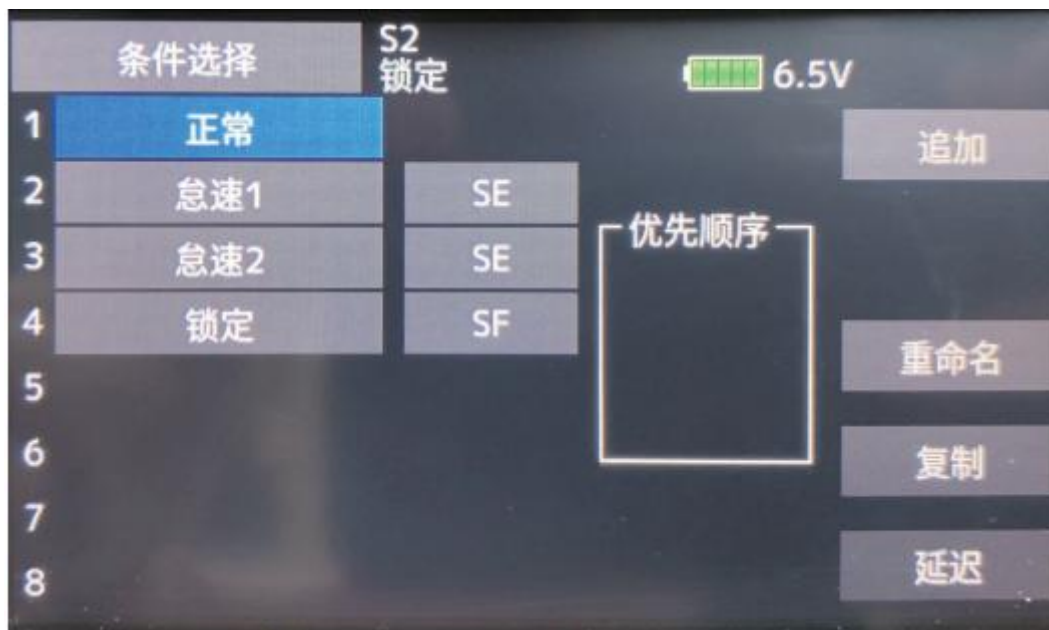
2. 类别设置成直升机

Category is set to Helicopter

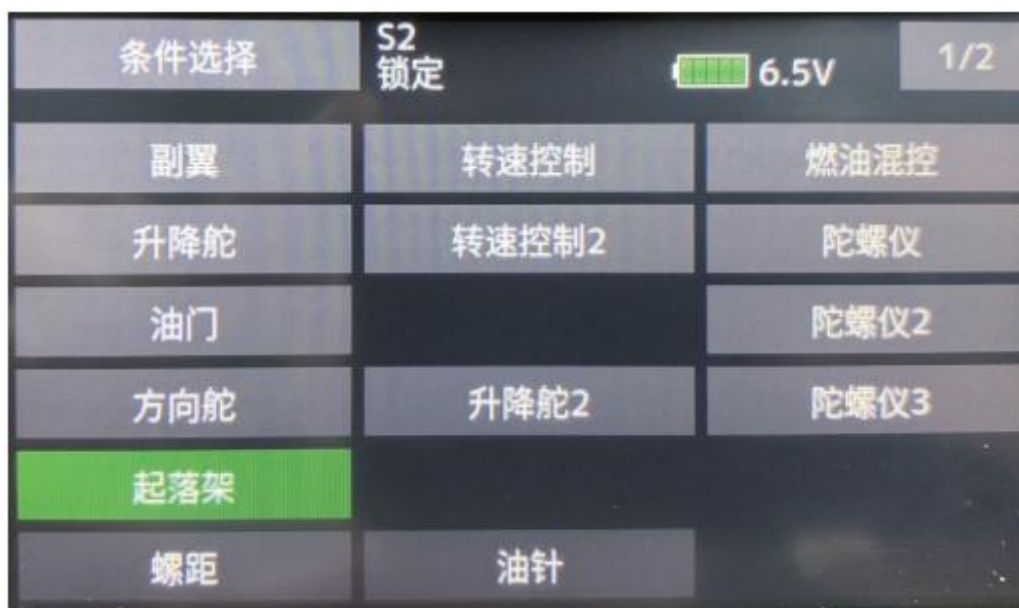


3. 设置油门锁定（HOLD）

Setting the throttle hold (HOLD)



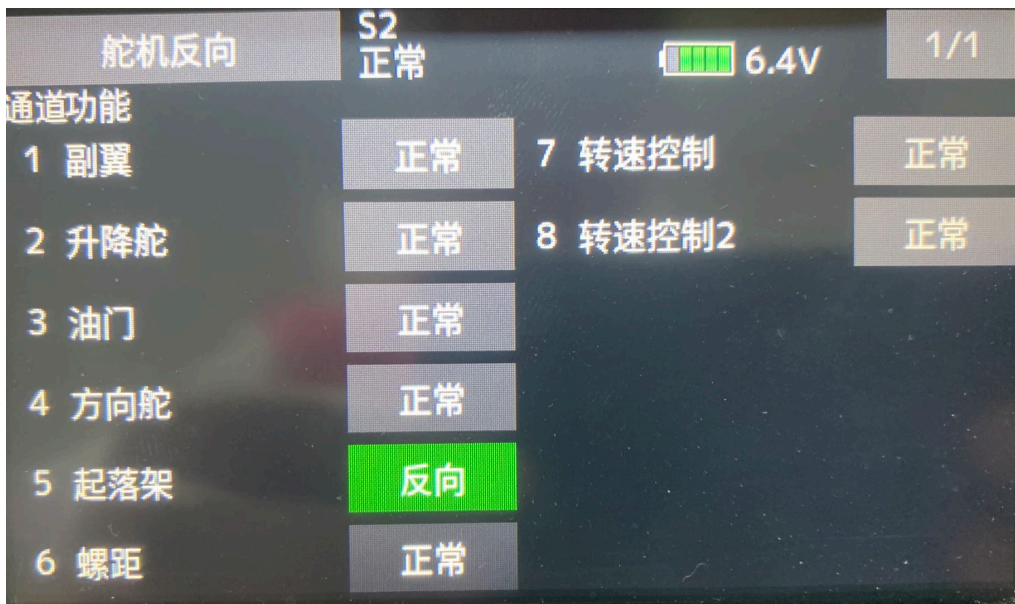
4. 设置 CH5 为起落架模式，设置开关用于控制姿态模式/3D 手动模式切换
 Set CH5 as landing gear mode, and set the switch to control attitude mode/3D manual mode switching





5. 进入舵机设置正反向界面

Enter the servo setting forward and reverse interface.

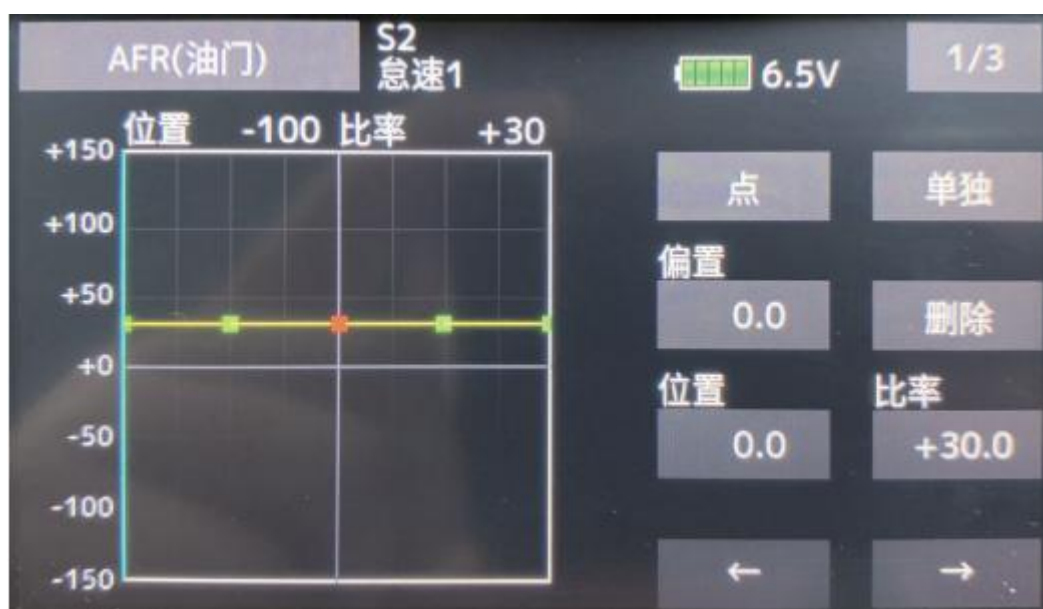
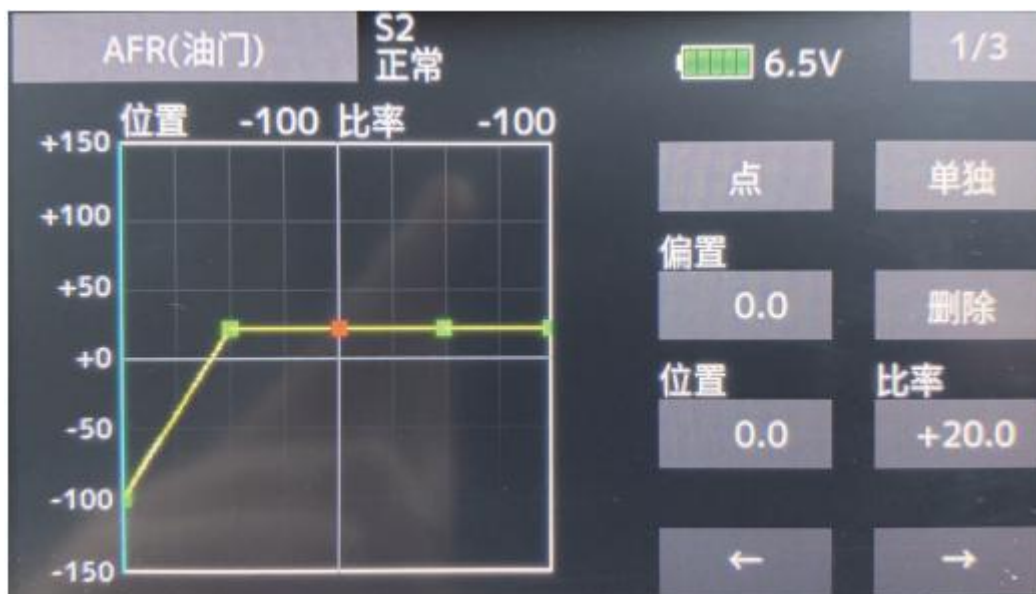


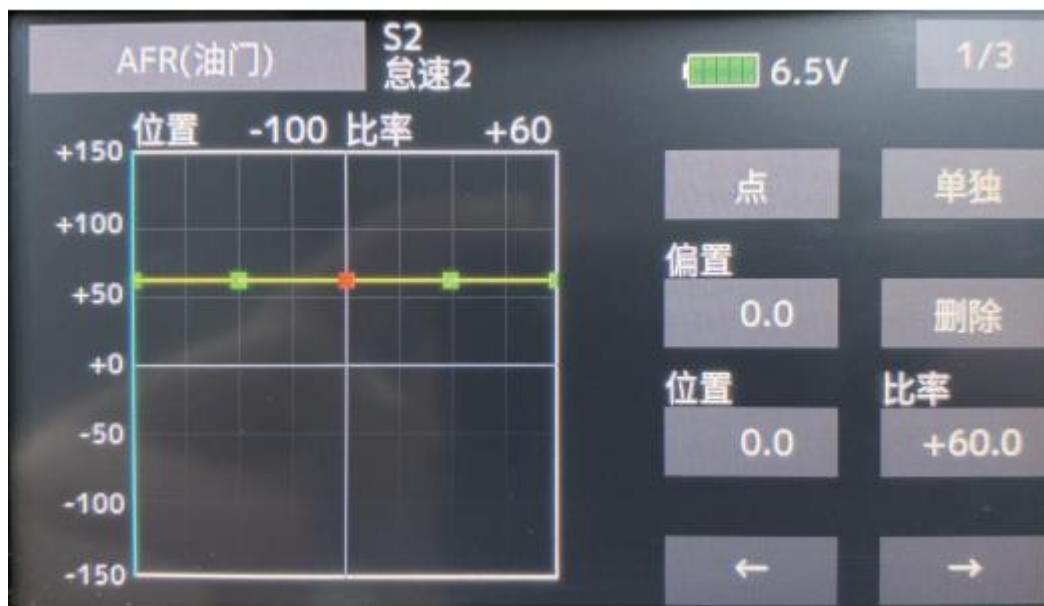
注：需要将油门的反向调整到正常 (NORM) 状态

Note: The reverse of the throttle needs to be adjusted to the normal (NORM) state

6. 设置油门曲线 NORMAL、IDLE 1\IDLE 2

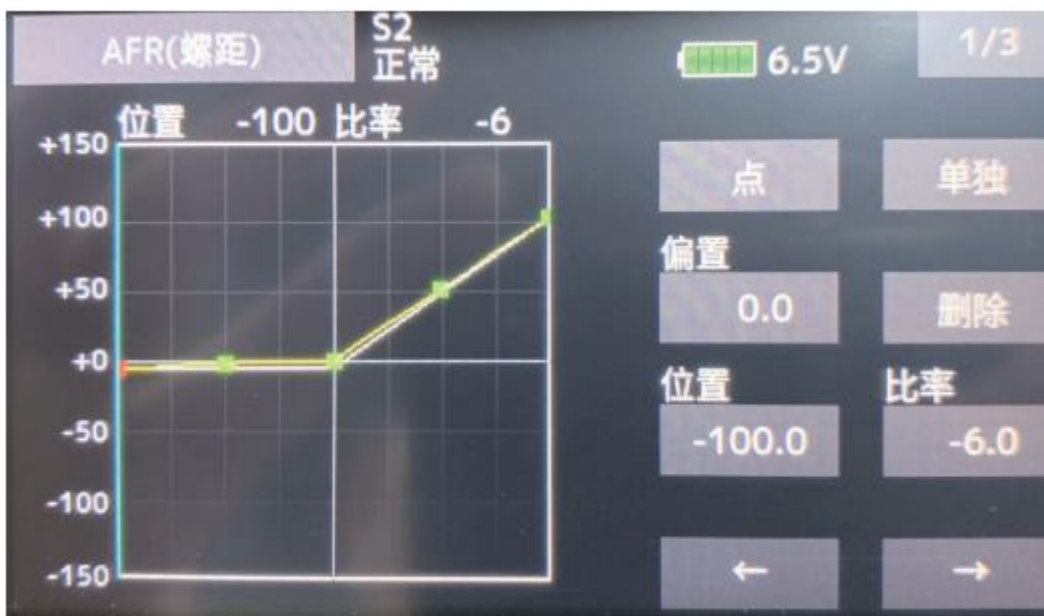
Set throttle curve NORMAL, IDLE 1\IDLE 2

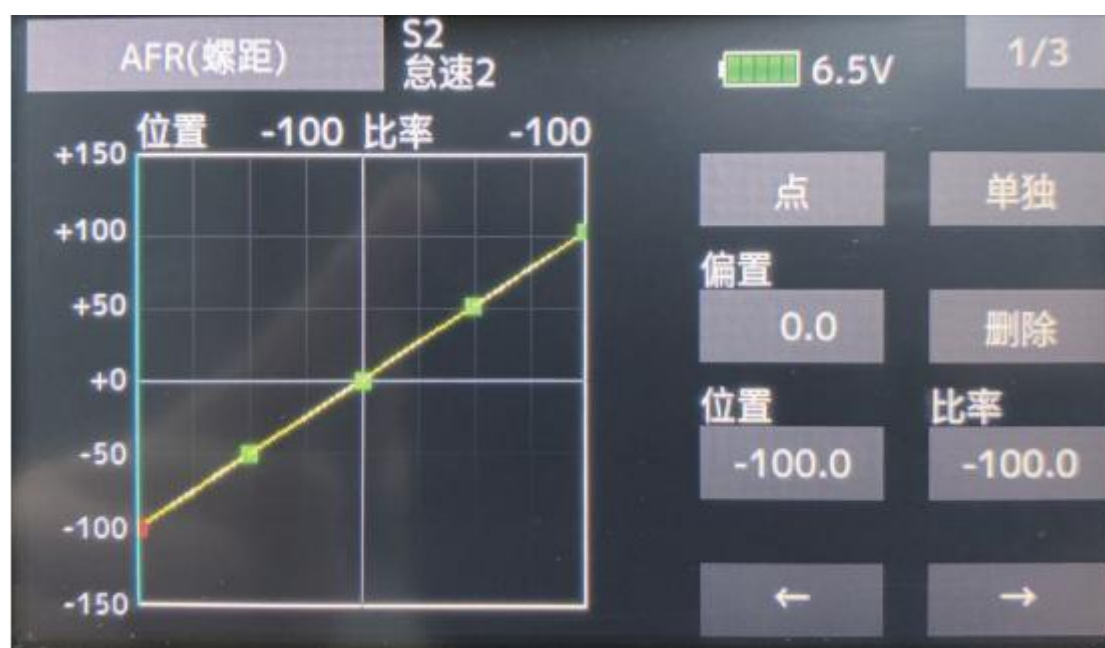
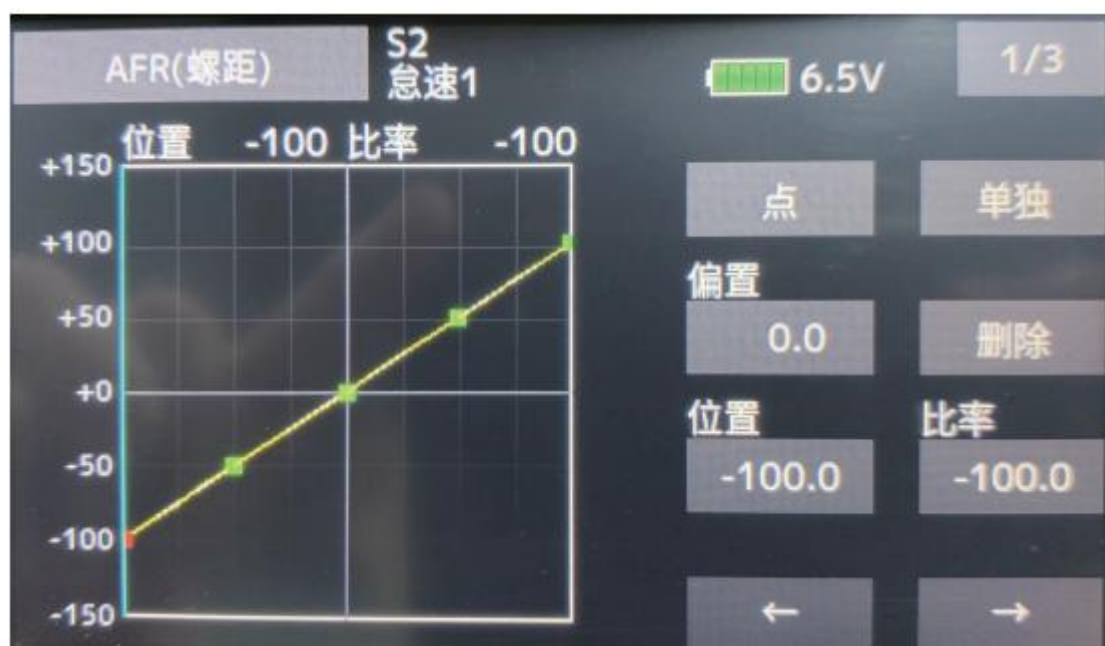




7. 设置螺距曲线 NORMAL、IDLE 1\IDLE 2

Set pitch curve NORMAL, IDLE 1\IDLE 2





8. 遥控器与飞行器绑定 The remote control is bound to the aircraft

(1) 打开遥控器通上飞机电池, 长按飞控, 侧方 (BIMD) 对码按钮 3 秒, 等到飞控自检通过, 对码成功。
(S-FHSS 协议直接对码)

(1) Turn on the remote control to connect the aircraft battery, press and hold the flight controller, the side (BIMD) code button for 3 seconds, wait until the flight control self-check passes, and the code is successful.

(S-FHSS protocol direct code matching)

